

## Advance Information

### 5.0 A H-Bridge with Load Current Feedback

The 33887 is a monolithic H-Bridge Power IC with a load current feedback feature making it ideal for closed-loop DC motor control. The IC incorporates internal control logic, charge pump, gate drive, and low  $R_{DS(ON)}$  MOSFET output circuitry. The 33887 is able to control inductive loads with continuous DC load currents up to 5.0 A, and with peak current active limiting between 5.2 A and 7.8 A. Output loads can be pulse width modulated (PWM-ed) at frequencies up to 10 kHz. The load current feedback feature provides a proportional (1/375th of the load current) constant-current output suitable for monitoring by a microcontroller's A/D input. This feature facilitates the design of closed-loop torque/speed control.

A Fault Status output terminal reports undervoltage, short circuit, and overtemperature conditions. Two independent inputs provide polarity control of two half-bridge totem-pole outputs. Two disable inputs force the H-Bridge outputs to tri-state (exhibit high impedance).

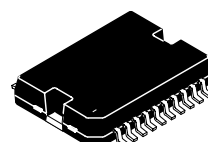
The 33887 is parametrically specified over a temperature range of  $-40^{\circ}\text{C} \leq T_A \leq 125^{\circ}\text{C}$  and a voltage range of  $5.0\text{ V} \leq V_+ \leq 28\text{ V}$ . The IC can also be operated up to 40 V with derating of the specifications.

#### Features

- 5.0 V to 40 V Continuous Operation
- 120 mΩ  $R_{DS(ON)}$  H-Bridge MOSFETs
- TTL/CMOS Compatible Inputs
- PWM Frequencies up to 10 kHz
- Active Current Limiting via Internal Constant OFF-Time PWM (with Temperature-Dependent Threshold Reduction)
- Output Short Circuit Protection with Shutdown
- Undervoltage Shutdown
- Fault Status Reporting
- Sleep Mode with Current Draw  $\leq 50\text{ }\mu\text{A}$

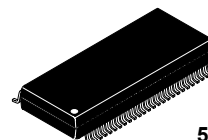
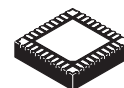
**33887**

### 5.0 A H-BRIDGE WITH LOAD CURRENT FEEDBACK



**DH SUFFIX**  
**CASE 979A**  
**20-TERMINAL HSOP**

**PNB SUFFIX**  
**CASE 1503**  
**36-TERMINAL PQFN**

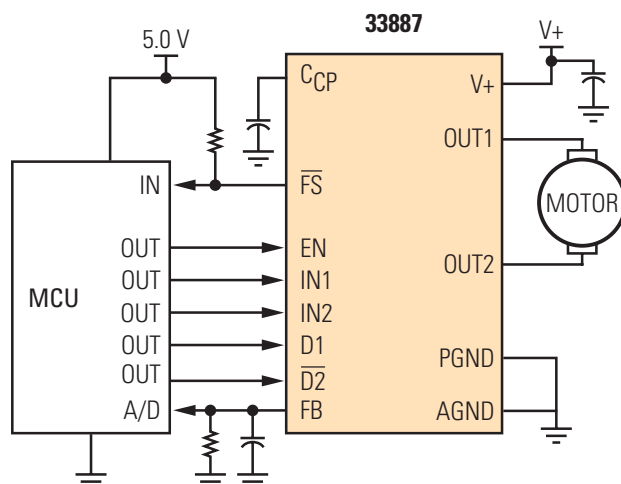


**DWB SUFFIX**  
**CASE 1390**  
**54-TERMINAL SOICW-EP**

#### ORDERING INFORMATION

Device	Temperature Range ( $T_A$ )	Package
MC33887DH/R2	$-40^{\circ}\text{C}$ to $125^{\circ}\text{C}$	20 HSOP
MC33887PNB/R2		36 PQFN
MC33887DWB/R2		54 SOICW-EP

**33887 Simplified Application Diagram**



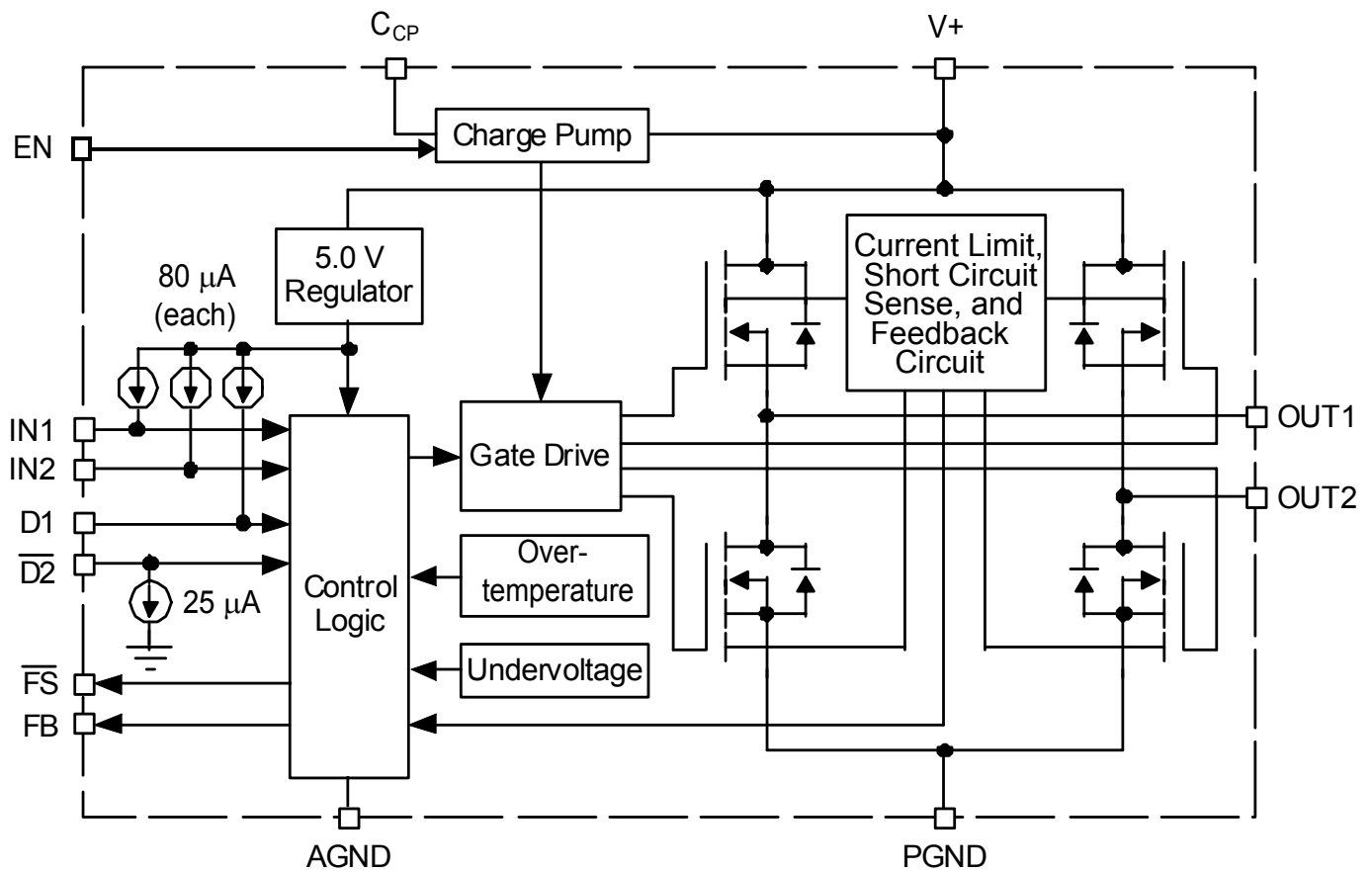
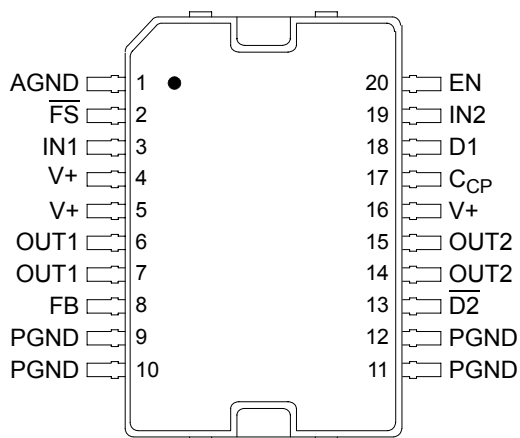


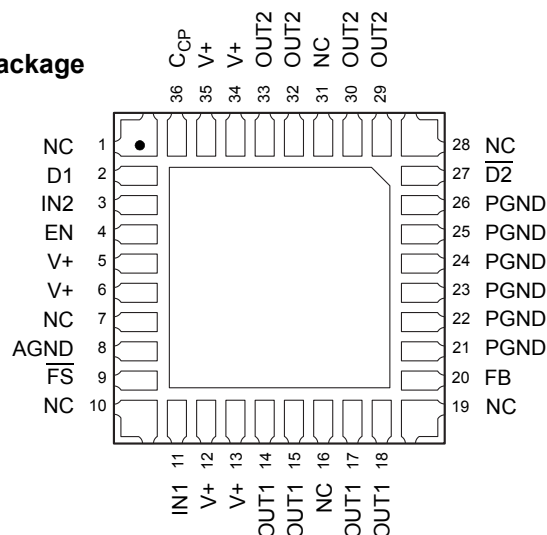
Figure 1. 33887 Simplified Internal Block Diagram



## HSOP TERMINAL FUNCTION DESCRIPTION

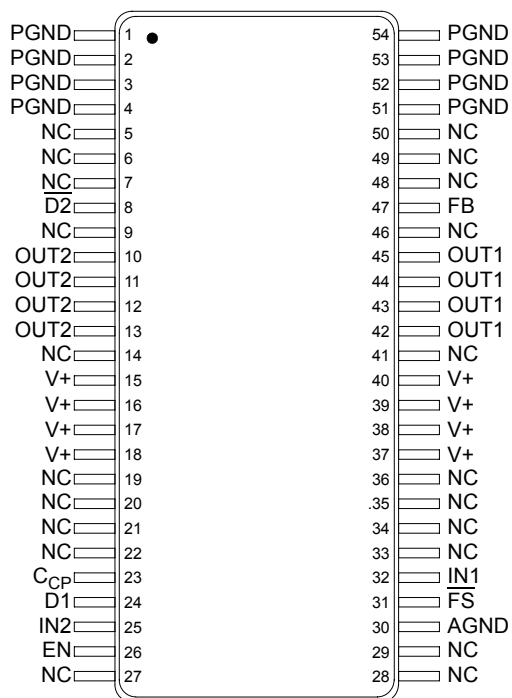
Terminal	Terminal Name	Formal Name	Definition
1	AGND	Analog Ground	Low-current analog signal ground.
2	FS	Fault Status for H-Bridge	Open drain active LOW Fault Status output requiring a pull-up resistor to 5.0 V.
3	IN1	Logic Input Control 1	Logic input control of OUT1 (i.e., IN1 logic HIGH = OUT1 HIGH).
4, 5, 16	V+	Positive Power Supply	Positive supply connections.
6, 7	OUT1	H-Bridge Output 1	Output 1 of H-Bridge.
8	FB	Feedback for H-Bridge	Current sensing feedback output providing ground referenced 1/375th (0.00266) of H-Bridge high-side current.
9–12	PGND	Power Ground	High-current power ground.
13	D2	Disable 2	Active LOW input used to simultaneously tri-state disable both H-Bridge outputs. When D2 is Logic LOW, both outputs are tri-stated.
14, 15	OUT2	H-Bridge Output 2	Output 2 of H-Bridge.
17	CCP	Charge Pump Capacitor	External reservoir capacitor connection for internal charge pump capacitor.
18	D1	Disable 1	Active HIGH input used to simultaneously tri-state disable both H-Bridge outputs. When D1 is Logic HIGH, both outputs are tri-stated.
19	IN2	Logic Input Control 2	Logic input control of OUT2 (i.e., IN2 logic HIGH = OUT2 HIGH).
20	EN	Enable	Logic input Enable control of device (i.e., EN logic High = full operation, EN logic LOW = Sleep Mode).

## Transparent Top View of Package



## PQFN TERMINAL FUNCTION DESCRIPTION

Terminal	Terminal Name	Formal Name	Definition
1, 7, 10, 16, 19, 28, 31	NC	No Connect	No internal connection to this terminal.
2	D1	Disable 1	Active HIGH input used to simultaneously tri-state disable both H-Bridge outputs. When D1 is Logic HIGH, both outputs are tri-stated.
3	IN2	Logic Input Control 2	Logic input control of OUT2 (i.e., IN2 logic HIGH = OUT2 HIGH).
4	EN	Enable	Logic input Enable control of device (i.e., EN logic HIGH = full operation, EN logic LOW = Sleep Mode).
5, 6, 12, 13, 34, 35	V+	Positive Power Supply	Positive supply connections.
8	AGND	Analog Ground	Low-current analog signal ground.
9	FS	Fault Status for H-Bridge	Open drain active LOW Fault Status output requiring a pull-up resistor to 5.0 V.
11	IN1	Logic Input Control 1	Logic input control of OUT1 (i.e., IN1 logic HIGH = OUT1 HIGH).
14, 15, 17, 18	OUT1	H-Bridge Output 1	Output 1 of H-Bridge.
20	FB	Feedback for H-Bridge	Current feedback output providing ground referenced 1/375th ratio of H-Bridge high-side current.
21–26	PGND	Power Ground	High-current power ground.
27	D2	Disable 2	Active LOW input used to simultaneously tri-state disable both H-Bridge outputs. When D2 is Logic LOW, both outputs are tri-stated.
29, 30, 32, 33	OUT2	H-Bridge Output 2	Output 2 of H-Bridge.
36	C <sub>CP</sub>	Charge Pump Capacitor	External reservoir capacitor connection for internal charge pump capacitor.



#### SOICW-EP TERMINAL FUNCTION DESCRIPTION

Terminal	Terminal Name	Formal Name	Definition
1–4, 51–54	PGND	Power Ground	High-current power ground.
5–7, 9, 14, 19–22, 27–29, 33–36, 41, 46, 48–50	NC	No Connect	No internal connection to this terminal.
8	$\overline{D2}$	Disable 2	Active LOW input used to simultaneously tri-state disable both H-Bridge outputs. When D2 is Logic LOW, both outputs are tri-stated.
10–13	OUT2	H-Bridge Output 2	Output 2 of H-Bridge.
15–18, 37–40	V+	Positive Power Supply	Positive supply connections.
23	C <sub>CP</sub>	Charge Pump Capacitor	External reservoir capacitor connection for internal charge pump capacitor.
24	D1	Disable 1	Active HIGH input used to simultaneously tri-state disable both H-Bridge outputs. When D1 is Logic HIGH, both outputs are tri-stated.
25	IN2	Logic Input Control 2	Logic input control of OUT2 (i.e., IN2 logic HIGH = OUT2 HIGH).
26	EN	Enable	Logic input Enable control of device (i.e., EN logic HIGH = full operation, EN logic LOW = Sleep Mode).
30	AGND	Analog Ground	Low-current analog signal ground.
31	$\overline{FS}$	Fault Status for H-Bridge	Open drain active LOW Fault Status output requiring a pull-up resistor to 5.0 V.
32	IN1	Logic Input Control 1	Logic input control of OUT1 (i.e., IN1 logic HIGH = OUT1 HIGH).
42–45	OUT1	H-Bridge Output 1	Output 1 of H-Bridge.
47	FB	Feedback for H-Bridge	Current feedback output providing ground referenced 1/375th ratio of H-Bridge high-side current.

## MAXIMUM RATINGS

All voltages are with respect to ground unless otherwise noted.

Rating	Symbol	Value	Unit
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## ELECTRICAL RATINGS

Supply Voltage	V+	40	V
Input Voltage (Note 1)	V <sub>IN</sub>	-0.1 to 7.0	V
$\overline{\text{FS}}$ Status Output (Note 2)	V <sub><math>\overline{\text{FS}}</math></sub>	7.0	V
Continuous Current (Note 3)	I <sub>OUT</sub>	5.0	A
HSOP ESD Voltage Human Body Model (Note 4) Each Terminal to AGND Each Terminal to PGND Each Terminal to V+ Each I/O to All Other I/Os Machine Model (Note 5)	V <sub>ESD1</sub> V <sub>ESD1</sub> V <sub>ESD1</sub> V <sub>ESD1</sub> V <sub>ESD2</sub>	±1000 ±1500 ±2000 ±2000 ±200	V
PQFN ESD Voltage Human Body Model (Note 4) Machine Model (Note 5)	V <sub>ESD1</sub> V <sub>ESD2</sub>	TBD TBD	V
SOICW-EP ESD Voltage Human Body Model (Note 4) Machine Model (Note 5)	V <sub>ESD1</sub> V <sub>ESD2</sub>	±1600 ±200	V

## THERMAL RATINGS

Storage Temperature	T <sub>STG</sub>	-65 to 150	°C
Ambient Operating Temperature (Note 6)	T <sub>A</sub>	-40 to 125	°C
Operating Junction Temperature	T <sub>J</sub>	-40 to 150	°C
Terminal Soldering Temperature (Note 7) HSOP PQFN SOICW-EP	T <sub>SOLDER</sub>	220 260 240	°C

### Notes

- Exceeding the input voltage on IN1, IN2, EN, D1, or  $\overline{\text{D2}}$  may cause a malfunction or permanent damage to the device.
- Exceeding the pull-up resistor voltage on the open Drain  $\overline{\text{FS}}$  terminal may cause permanent damage to the device.
- Continuous current capability so long as junction temperature is  $\leq 150^\circ\text{C}$ .
- ESD1 testing is performed in accordance with the Human Body Model ( $C_{\text{ZAP}} = 100 \text{ pF}$ ,  $R_{\text{ZAP}} = 1500 \Omega$ ).
- ESD2 testing is performed in accordance with the Machine Model ( $C_{\text{ZAP}} = 200 \text{ pF}$ ,  $R_{\text{ZAP}} = 0 \Omega$ ).
- The limiting factor is junction temperature, taking into account the power dissipation, thermal resistance, and heat sinking.
- Terminal soldering temperature limit is for 10 seconds maximum duration. Not designed for immersion soldering. Exceeding these limits may cause malfunction or permanent damage to the device.

**MAXIMUM RATINGS (continued)**

All voltages are with respect to ground unless otherwise noted.

Rating	Symbol	Value	Unit
<b>THERMAL RESISTANCE (AND PACKAGE DISSIPATION) RATINGS</b> (Note 8), (Note 9), (Note 10), (Note 11)			
Junction-to-Board (Bottom) HSOP (6.0 W) PQFN (4.0 W) SOICW-EP (2.0 W)	$R_{\theta JB}$	~5.0 ~4.3 ~8.0	°C/W
Junction-to-Ambient, Natural Convection, Single-Layer Board (1s) (Note 12) HSOP (6.0 W) PQFN (4.0 W) SOICW-EP (2.0 W)	$R_{\theta JA}$	~41 ~TBD ~62	°C/W
Junction-to-Ambient, Natural Convection, Four-Layer Board (2s2p) (Note 13) HSOP (6.0 W) PQFN (4.0 W) SOICW-EP (2.0 W)	$R_{\theta JMA}$	~30 ~21.3 ~TBD	°C/W
Junction-to-Case (Top) (Note 14) HSOP (6.0 W) PQFN (4.0 W) SOICW-EP (2.0 W)	$R_{\theta JC}$	~0.5 ~0.9 ~1.5	°C/W

**Notes**

8. The limiting factor is junction temperature, taking into account the power dissipation, thermal resistance, and heat sinking.
9. Exposed heatsink pad plus the power and ground terminals comprise the main heat conduction paths. The actual  $R_{\theta JB}$  (junction-to-PC board) values will vary depending on solder thickness and composition and copper trace thickness.
10. Thermal resistance between the die and the printed circuit board per JEDEC JESD51-8. Board temperature is measured on the top surface of the board near the package.
11. Junction temperature is a function of on-chip power dissipation, package thermal resistance, mounting site (board) temperature, ambient temperature, air flow, power dissipation of other components on the board, and board thermal resistance.
12. Per SEMI G38-87 and JEDEC JESD51-2 with the single-layer board (JESD51-3) horizontal.
13. Per JEDEC JESD51-6 with the board horizontal.
14. Indicates the average thermal resistance between the die and the case top surface as measured by the cold plate method (MIL SPEC-883 Method 1012.1) with the cold plate temperature used for the case temperature.

## STATIC ELECTRICAL CHARACTERISTICS

Characteristics noted under conditions  $5.0\text{ V} \leq V^+ \leq 28\text{ V}$  and  $-40^\circ\text{C} \leq T_A \leq 125^\circ\text{C}$  unless otherwise noted. Typical values noted reflect the approximate parameter mean at  $T_A = 25^\circ\text{C}$  under nominal conditions unless otherwise noted.

Characteristic	Symbol	Min	Typ	Max	Unit
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### POWER SUPPLY

Operating Voltage Range (Note 15)	$V^+$	5.0	—	40	V
Sleep State Supply Current (Note 16) $I_{OUT} = 0\text{ A}$ , $V_{EN} = 0\text{ V}$	$I_{Q(\text{sleep})}$	—	25	50	$\mu\text{A}$
Standby Supply Current $I_{OUT} = 0\text{ A}$ , $V_{EN} = 5.0\text{ V}$	$I_{Q(\text{standby})}$	—	—	20	mA
Threshold Supply Voltage Switch-OFF	$V^+_{(\text{thres-OFF})}$	4.15	4.4	4.65	V
Switch-ON	$V^+_{(\text{thres-ON})}$	4.5	4.75	5.0	V
Hysteresis	$V^+_{(\text{hys})}$	150	—	—	mV

### CHARGE PUMP

Charge Pump Voltage $V^+ = 5.0\text{ V}$ $8.0\text{ V} \leq V^+ \leq 40\text{ V}$	$V_{CP} - V^+$	3.35 —	— —	— 20	V
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### CONTROL INPUTS

Input Voltage (IN1, IN2, D1, $\overline{D2}$ ) Threshold HIGH Threshold LOW Hysteresis	$V_{IH}$ $V_{IL}$ $V_{HYS}$	3.5 — 0.7	— — 1.0	— 1.4 —	V
Input Current (IN1, IN2, D1) $V_{IN} = 0.0\text{ V}$	$I_{INP}$	-200	-80	—	$\mu\text{A}$
Input Current ( $\overline{D2}$ , EN) $V_{\overline{D2}} = 5.0\text{ V}$	$I_{INP}$	—	25	100	$\mu\text{A}$

#### Notes

- Specifications are characterized over the range of  $5.0\text{ V} \leq V^+ \leq 28\text{ V}$ . Operation  $>28\text{ V}$  will cause some parameters to exceed listed min/max values. Refer to typical operating curves to extrapolate values for operation  $>28\text{ V}$  but  $\leq 40\text{ V}$ .
- $I_{Q(\text{sleep})}$  is with sleep mode function enabled.

**STATIC ELECTRICAL CHARACTERISTICS (continued)**

Characteristics noted under conditions  $5.0\text{ V} \leq V_+ \leq 28\text{ V}$  and  $-40^\circ\text{C} \leq T_A \leq 125^\circ\text{C}$  unless otherwise noted. Typical values noted reflect the approximate parameter mean at  $T_A = 25^\circ\text{C}$  under nominal conditions unless otherwise noted.

Characteristic	Symbol	Min	Typ	Max	Unit
<b>POWER OUTPUTS (OUT1, OUT2)</b>					
Output-ON Resistance (Note 17) $5.0\text{ V} \leq V_+ \leq 28\text{ V}$ , $T_J = 25^\circ\text{C}$ $8.0\text{ V} \leq V_+ \leq 28\text{ V}$ , $T_J = 150^\circ\text{C}$ $5.0\text{ V} \leq V_+ \leq 8.0\text{ V}$ , $T_J = 150^\circ\text{C}$	$R_{DS(ON)}$	– – –	120 – –	– 225 300	$\text{m}\Omega$
Active Current Limiting Threshold (via Internal Constant OFF-Time PWM)	$I_{LIM}$	5.2	6.5	7.8	A
High-Side Short Circuit Detection Threshold	$I_{SCH}$	11	–	–	A
Low-Side Short Circuit Detection Threshold	$I_{SCL}$	8.0	–	–	A
Leakage Current (Note 18) $V_{OUT} = V_+$ $V_{OUT} = \text{Ground}$	$I_{OUT(leak)}$	– –	100 30	200 60	$\mu\text{A}$
Output FET Body Diode Forward Voltage Drop $I_{OUT} = 3.0\text{ A}$	$V_F$	–	–	2.0	V
Overtemperature Shutdown Thermal Limit Hysteresis	$T_{LIM}$ $T_{HYS}$	175 10	– –	– 30	$^\circ\text{C}$

**HIGH-SIDE CURRENT SENSE FEEDBACK**

Feedback Current $I_{OUT} = 0\text{ mA}$ $I_{OUT} = 500\text{ mA}$ $I_{OUT} = 1.5\text{ A}$ $I_{OUT} = 3.0\text{ A}$ $I_{OUT} = 6.0\text{ A}$	$I_{FB}$	– 1.07 3.6 7.2 14.4	– 1.33 4.0 8.0 16	600 1.60 4.4 8.8 17.6	$\mu\text{A}$ mA mA mA mA
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**FAULT STATUS (Note 19)**

Fault Status Leakage Current (Note 20) $V_{FS} = 5.0\text{ V}$	$I_{FS(leak)}$	–	–	10	$\mu\text{A}$
Fault Status SET Voltage (Note 21) $I_{FS} = 300\text{ }\mu\text{A}$	$V_{FS(LOW)}$	–	–	1.0	V

**Notes**

- Output-ON resistance as measured from output to  $V_+$  and ground.
- Outputs switched OFF with D1 or  $\overline{D2}$ .
- Fault Status output is an open Drain output requiring a pull-up resistor to 5.0 V.
- Fault Status Leakage Current is measured with Fault Status HIGH and *not* SET.
- Fault Status Set Voltage is measured with Fault Status LOW and SET with  $I_{FS} = 300\text{ }\mu\text{A}$ .

## DYNAMIC ELECTRICAL CHARACTERISTICS

Characteristics noted under conditions  $5.0\text{ V} \leq V_+ \leq 28\text{ V}$  and  $-40^\circ\text{C} \leq T_A \leq 125^\circ\text{C}$  unless otherwise noted. Typical values noted reflect the approximate parameter mean at  $T_A = 25^\circ\text{C}$  under nominal conditions unless otherwise noted.

Characteristic	Symbol	Min	Typ	Max	Unit
<b>TIMING CHARACTERISTICS</b>					
PWM Frequency (Note 22)	$f_{\text{PWM}}$	–	10	–	kHz
Maximum Switching Frequency During Active Current Limiting (Note 23)	$f_{\text{MAX}}$	–	–	20	kHz
Output ON Delay (Note 24) $V_+ = 14\text{ V}$	$t_{\text{d(ON)}}$	–	–	18	$\mu\text{s}$
Output OFF Delay (Note 24) $V_+ = 14\text{ V}$	$t_{\text{d(OFF)}}$	–	–	18	$\mu\text{s}$
Output Latch-OFF Time	$t_a$	15	20.5	26	$\mu\text{s}$
Output Blanking Time	$t_b$	12	16.5	21	$\mu\text{s}$
Output Rise and Fall Time (Note 25) $V_+ = 14\text{ V}, I_{\text{OUT}} = 3.0\text{ A}$	$t_f, t_r$	2.0	5.0	8.0	$\mu\text{s}$
Short Circuit/Overtemperature Turn-OFF Time (Note 26)	$t_{\text{FAULT}}$	–	4.0	–	$\mu\text{s}$
Disable Delay Time (Note 27)	$t_{\text{d(disable)}}$	–	–	8.0	$\mu\text{s}$
Power-ON Delay Time (Note 28)	$t_{\text{pod}}$	–	1.0	5.0	ms
Wake-Up Delay Time (Note 28)	$t_{\text{wud}}$	–	1.0	5.0	ms
Output FET Body Diode Reverse Recovery Time (Note 29)	$t_{\text{rr}}$	100	–	–	ns

### Notes

22. The outputs can be PWM-controlled from an external source. This is typically done by holding one input high while applying a PWM pulse train to the other input. The maximum PWM frequency obtainable is a compromise between switching losses and switching frequency. See Typical Switching Waveforms, [Figures 11](#) through [18](#), pp. 15–16.
23. The Maximum Switching Frequency during active current limiting is internally implemented. The internal control produces a constant OFF-time PWM of the output. The output load characteristics affect the switching frequency.
24. Output Delay is the time duration from the midpoint of the IN1 or IN2 input signal to the 10% or 90% point (dependent on the transition direction) of the OUT1 or OUT2 signal. If the output is transitioning HIGH-to-LOW, the delay is from the midpoint of the input signal to the 90% point of the output response signal. If the output is transitioning LOW-to-HIGH, the delay is from the midpoint of the input signal to the 10% point of the output response signal. See [Figure 2](#), page 11.
25. Rise Time is from the 10% to the 90% level and Fall Time is from the 90% to the 10% level of the output signal. See [Figure 4](#), page 11.
26. Increasing currents will become limited at  $I_{\text{LIM}}$ . Hard shorts will breach the  $I_{\text{SCH}}$  or  $I_{\text{SCL}}$  limit, forcing the output into an immediate tri-state latch-OFF. See [Figures 6](#) and [7](#), page 12. Active current limiting will cause junction temperatures to rise. A junction temperature above  $160^\circ\text{C}$  will cause the active current limiting to progressively “fold-back”, or decrease, to 2.5 A typical at  $175^\circ\text{C}$  where thermal latch-OFF will occur. See [Figure 5](#), page 11.
27. Disable Delay Time is the time duration from the midpoint of the D (disable) input signal to 10% of the output tri-state response. See [Figure 3](#), page 11.
28. Parameter has been characterized but not production tested.
29. Parameter is guaranteed by design but not production tested.

## Timing Diagrams

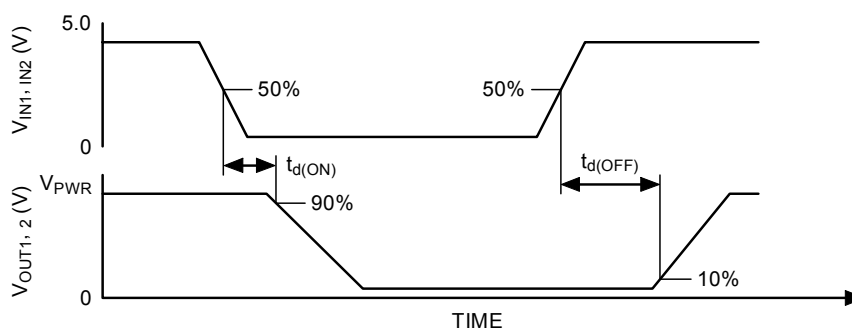


Figure 2. Output Delay Time

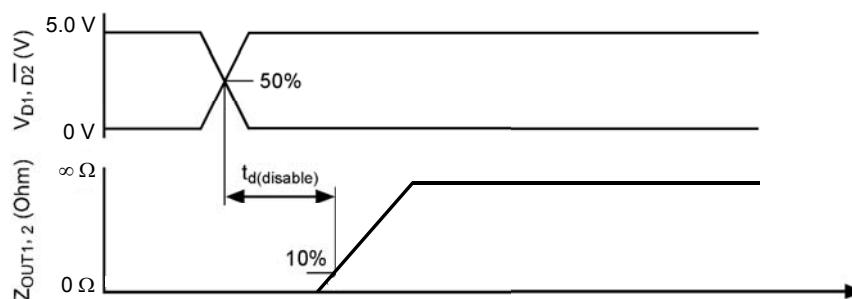


Figure 3. Disable Delay Time

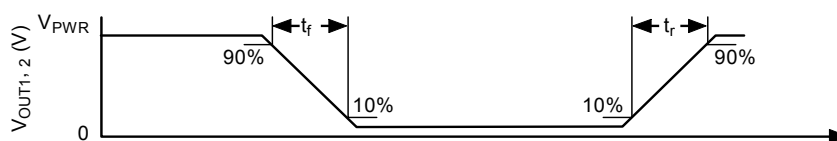


Figure 4. Output Switching Time

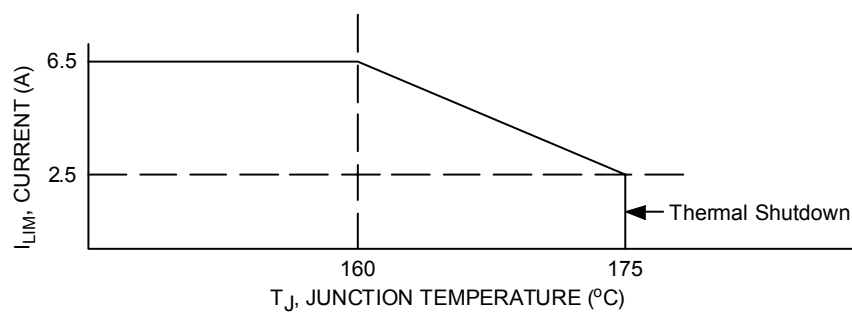


Figure 5. Active Current Limiting Versus Temperature (Typical)

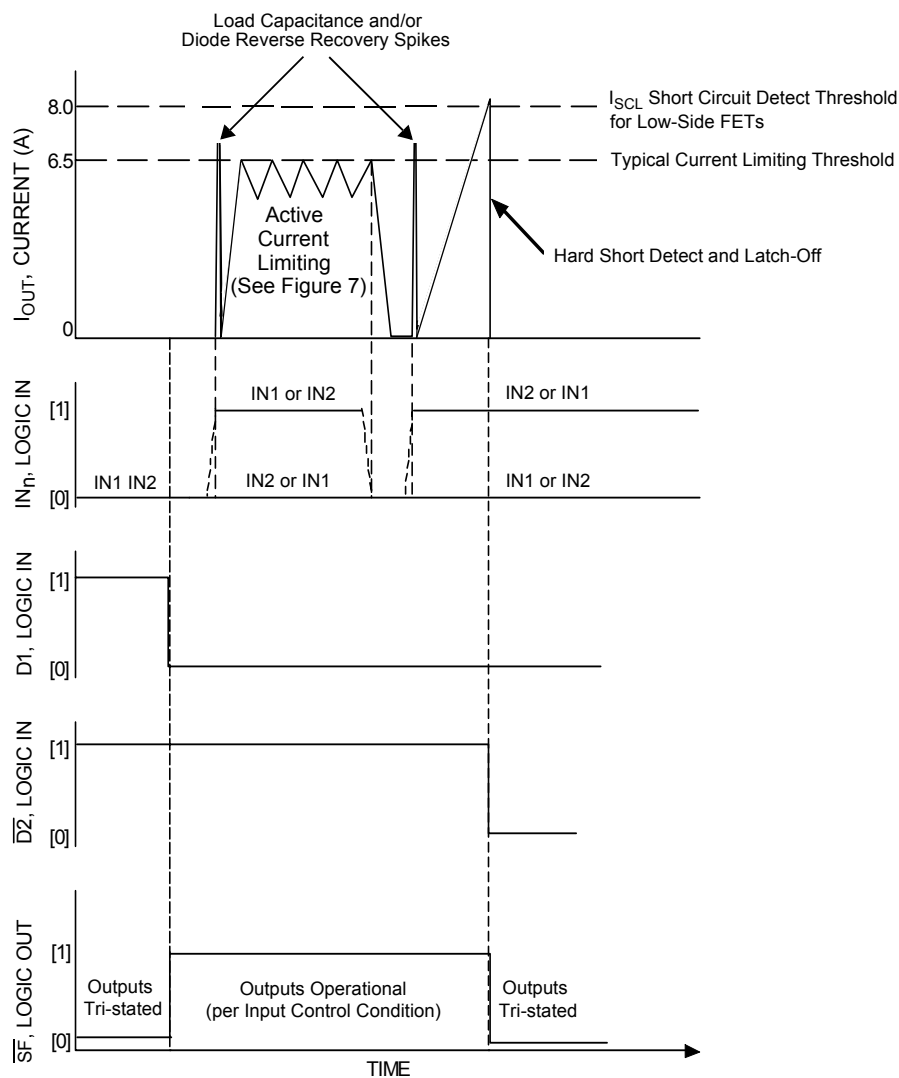


Figure 6. Active Current Limiting Versus Time

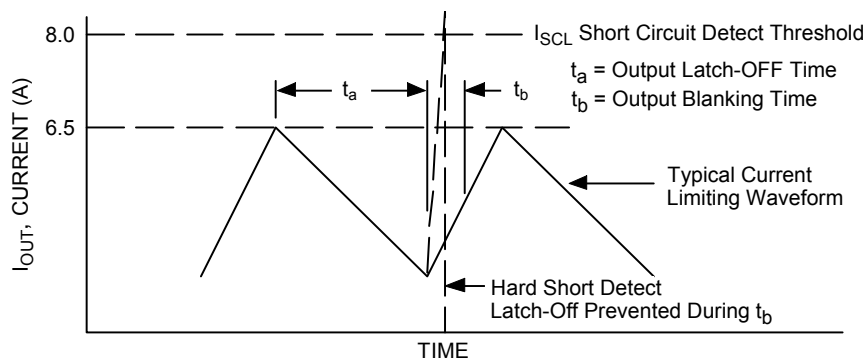


Figure 7. Active Current Limiting Detail

## Electrical Performance Curves

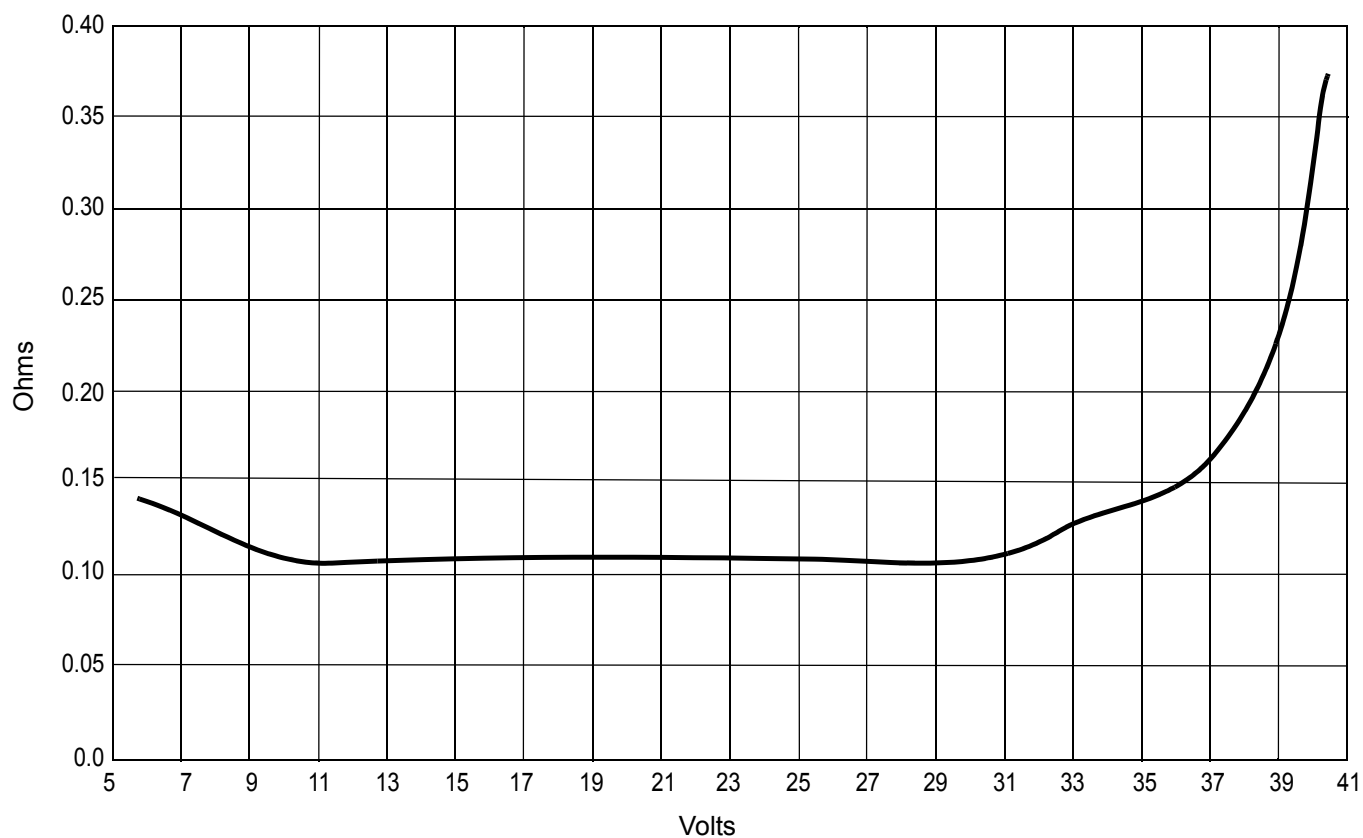


Figure 8. Typical High-Side  $R_{DS(ON)}$  Versus  $V_+$

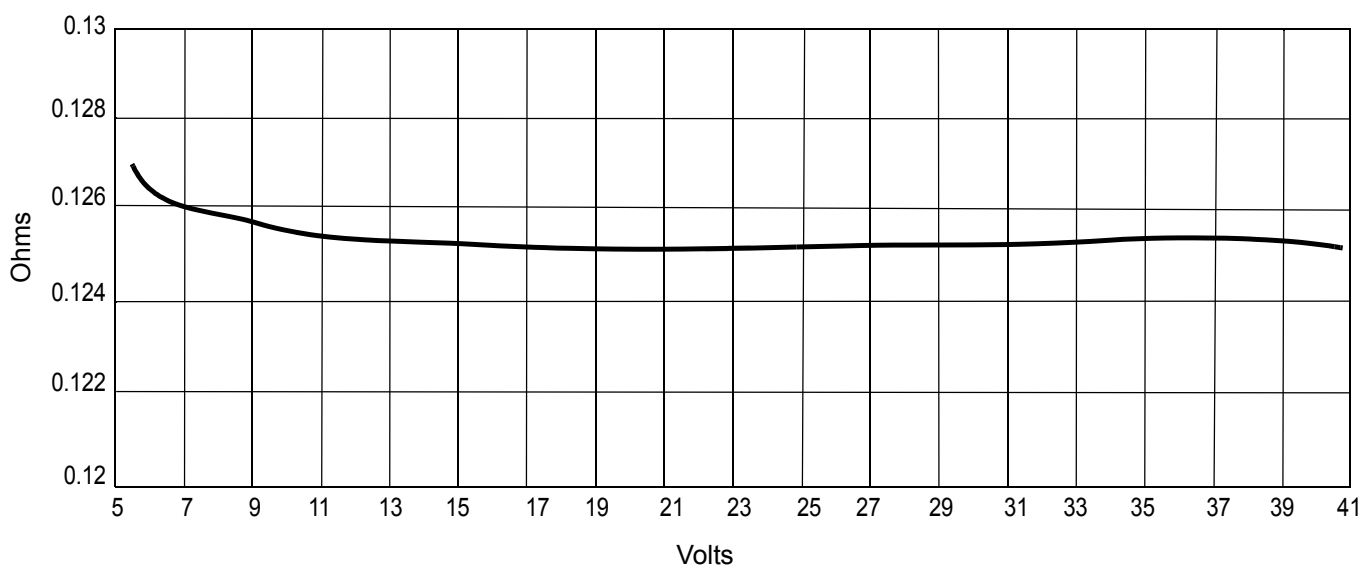
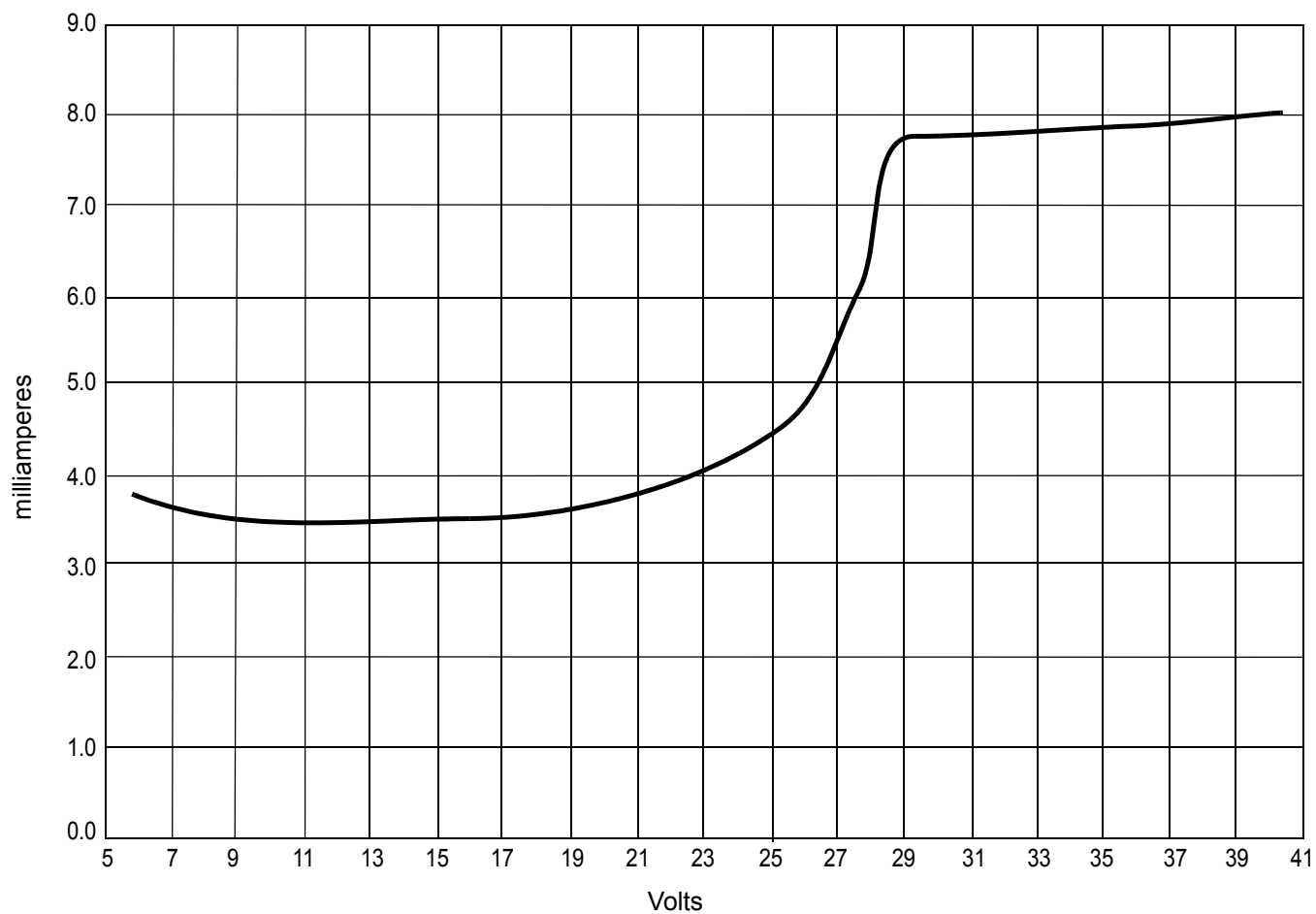


Figure 9. Typical Low-Side  $R_{DS(ON)}$  Versus  $V_+$

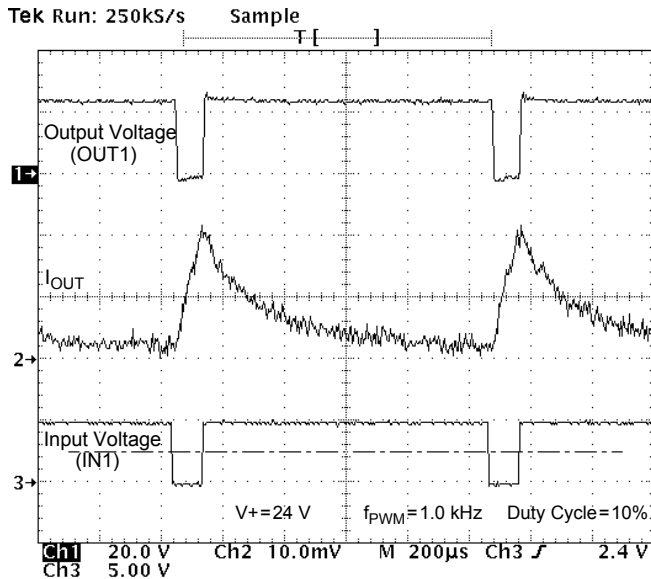


**Figure 10. Typical Quiescent Supply Current Versus V+**

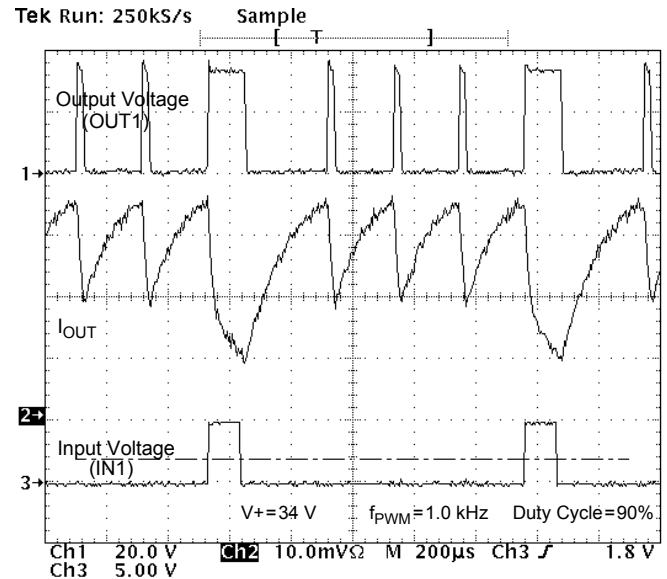
## Typical Switching Waveforms

**Important** For all plots, the following applies:

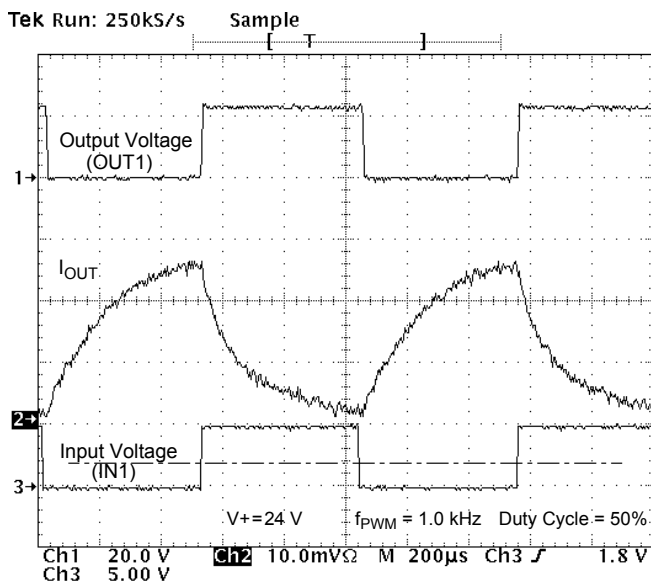
- Ch2=2.0 A per division
- $L_{LOAD}=533\ \mu\text{H}$  @ 1.0 kHz
- $L_{LOAD}=530\ \mu\text{H}$  @ 10.0 kHz
- $R_{LOAD}=4.0\ \Omega$



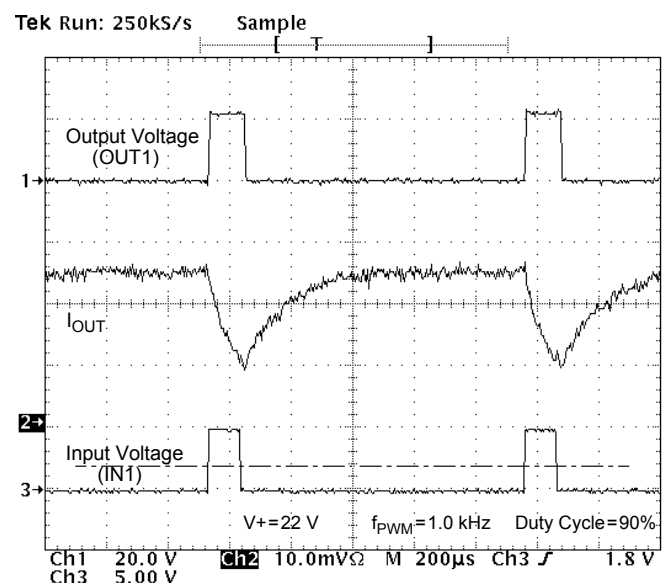
**Figure 11. Output Voltage and Current vs. Input Voltage at  $V^+ = 24\ \text{V}$ , PMW Frequency of 1.0 kHz, and Duty Cycle of 10%**



**Figure 13. Output Voltage and Current vs. Input Voltage at  $V^+ = 34\ \text{V}$ , PMW Frequency of 1.0 kHz, and Duty Cycle of 90%, Showing Device in Current Limiting Mode**



**Figure 12. Output Voltage and Current vs. Input Voltage at  $V^+ = 24\ \text{V}$ , PMW Frequency of 1.0 kHz, and Duty Cycle of 50%**



**Figure 14. Output Voltage and Current vs. Input Voltage at  $V^+ = 22\ \text{V}$ , PMW Frequency of 1.0 kHz, and Duty Cycle of 90%**

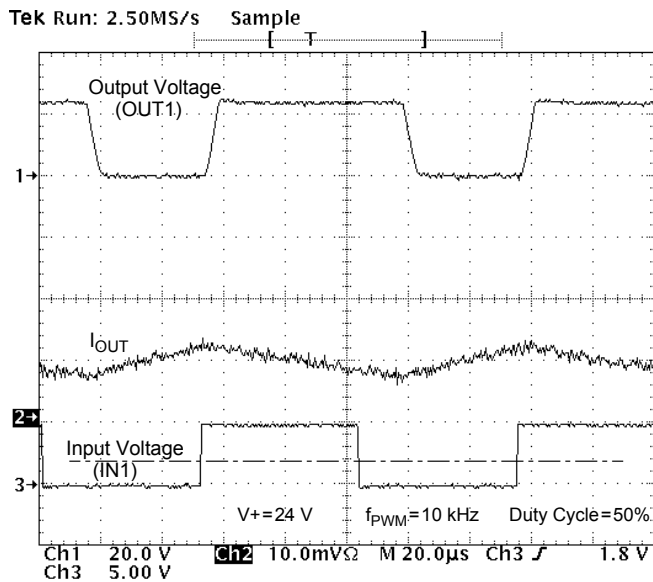


Figure 15. Output Voltage and Current vs. Input Voltage at  $V^+ = 24 \text{ V}$ , PMW Frequency of 10 kHz, and Duty Cycle of 50%

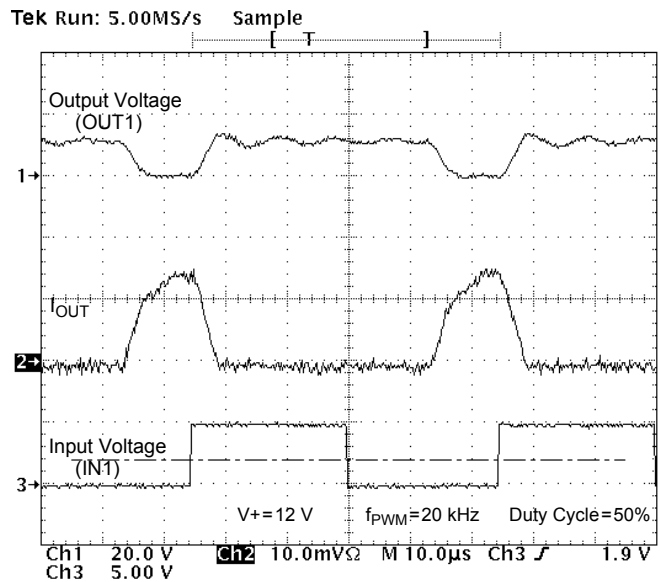


Figure 17. Output Voltage and Current vs. Input Voltage at  $V^+ = 12 \text{ V}$ , PMW Frequency of 20 kHz, and Duty Cycle of 50% for a Purely Resistive Load

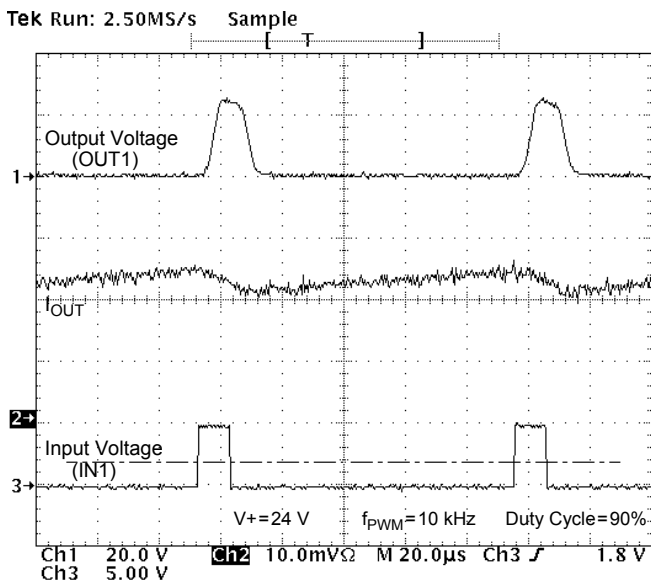


Figure 16. Output Voltage and Current vs. Input Voltage at  $V^+ = 24 \text{ V}$ , PMW Frequency of 10 kHz, and Duty Cycle of 90%

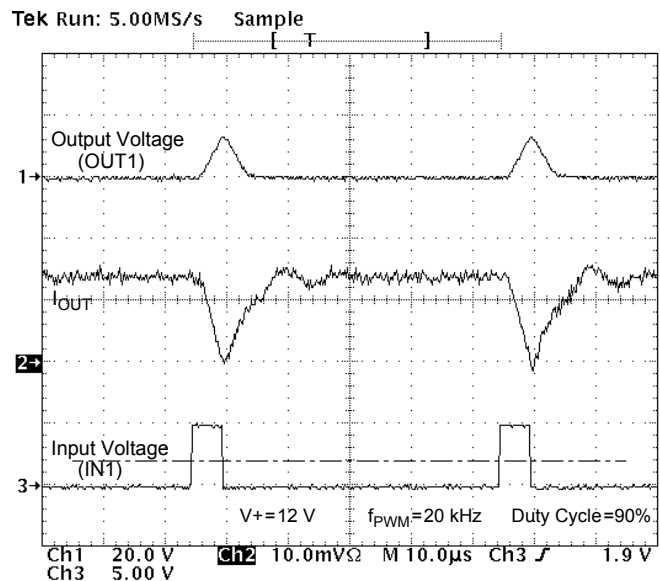


Figure 18. Output Voltage and Current vs. Input Voltage at  $V^+ = 12 \text{ V}$ , PMW Frequency of 20 kHz, and Duty Cycle of 90% for a Purely Resistive Load

**Table 1. Truth Table**

The tri-state conditions and the fault status are reset using D1 or  $\overline{D2}$ . The truth table uses the following notations: L = LOW, H = HIGH, X = HIGH or LOW, and Z = High impedance (all output power transistors are switched off).

Device State	Input Conditions					Fault Status Flag	Output States	
	EN	D1	$\overline{D2}$	IN1	IN2	$\overline{FS}$	OUT1	OUT2
Forward	H	L	H	H	L	H	H	L
Reverse	H	L	H	L	H	H	L	H
Output FET Body Diode Low	H	L	H	L	L	H	L	L
Output FET Body Diode High	H	L	H	H	H	H	H	H
Disable 1 (D1)	H	H	X	X	X	L	Z	Z
Disable 2 ( $\overline{D2}$ )	H	X	L	X	X	L	Z	Z
IN1 Disconnected	H	L	H	Z	X	H	H	X
IN2 Disconnected	H	L	H	X	Z	H	X	H
D1 Disconnected	H	Z	X	X	X	L	Z	Z
$\overline{D2}$ Disconnected	H	X	Z	X	X	L	Z	Z
Undervoltage (Note 30)	H	X	X	X	X	L	Z	Z
Overtemperature (Note 31)	H	X	X	X	X	L	Z	Z
Short Circuit (Note 31)	H	X	X	X	X	L	Z	Z
Sleep Mode EN	L	X	X	X	X	H	Z	Z
EN Disconnected	Z	X	X	X	X	H	Z	Z

**Notes**

30. In the case of an undervoltage condition, the outputs tri-state and the fault status is SET logic LOW. Upon undervoltage recovery, fault status is reset automatically or automatically cleared and the outputs are restored to their original operating condition.
31. When a short circuit or overtemperature condition is detected, the power outputs are tri-state latched-OFF independent of the input signals and the fault status flag is SET logic LOW.

## SYSTEM/APPLICATION INFORMATION

### INTRODUCTION

Numerous protection and operational features (speed, torque, direction, dynamic braking, PWM control, and closed-loop control), in addition to the 5.0 A current capability, make the 33887 a very attractive, cost-effective solution for controlling a broad range of small DC motors. In addition, a pair of 33887 devices can be used to control bipolar stepper motors. The 33887 can also be used to excite transformer primary windings with a switched square wave to produce secondary winding AC currents.

As shown in [Figure 1](#), Simplified Internal Block Diagram, page 2, the 33887 is a fully protected monolithic H-Bridge with Enable, Fault Status reporting, and High-Side current sense feedback to accommodate closed-loop PWM control. For a DC motor to run, the input conditions need be as follows: Enable input logic HIGH, D1 input logic LOW,  $\overline{D2}$  input logic HIGH,  $\overline{FS}$  flag cleared (logic HIGH), one IN logic LOW and the other IN logic HIGH (to define output polarity). The 33887 can execute dynamic braking by simultaneously turning on either both high-side MOSFETs or both low-side MOSFETs in the output H-Bridge; e.g., IN1 and IN2 logic HIGH or IN1 and IN2 logic LOW.

The 33887 outputs are capable of providing a continuous DC load current of 5.0 A from a 40 V V+ source. An internal charge pump supports PWM frequencies to 10 kHz. An external pull-up resistor is required at the  $\overline{FS}$  terminal for fault status reporting. The 33887 has an analog feedback (current mirror) output terminal (the FB terminal) that provides a constant-current source ratioed to the active high-side MOSFET. This can be

used to provide “real time” monitoring of load current to facilitate closed-loop operation for motor speed/torque control.

Two independent inputs (IN1 and IN2) provide control of the two totem-pole half-bridge outputs. Two disable inputs (D1 and  $\overline{D2}$ ) provide the means to force the H-Bridge outputs to a high-impedance state (all H-Bridge switches OFF). An EN terminal controls an enable function that allows the 33887 to be placed in a power-conserving sleep mode.

The 33887 has undervoltage shutdown with automatic recovery, active current limiting, output short-circuit latch-OFF, and overtemperature latch-OFF. An undervoltage shutdown, output short-circuit latch-OFF, or overtemperature latch-OFF fault condition will cause the outputs to turn OFF (i.e., become high impedance or tri-stated) and the fault output flag to be set LOW. Either of the Disable inputs or V+ must be “toggled” to clear the fault flag.

Active current limiting is accomplished by a constant OFF-time PWM method employing active current limiting threshold triggering. The active current limiting scheme is unique in that it incorporates a junction temperature-dependent current limit threshold. This means the active current limiting threshold is “ramped down” as the junction temperature increases above 160°C, until at 175°C the current will have been decreased to about 2.5 A. Above 175°C, the overtemperature shutdown (latch-OFF) occurs. This combination of features allows the device to remain in operation for a longer period of time with unexpected loads, while still retaining adequate protection for both the device and the load.

## FUNCTIONAL TERMINAL DESCRIPTION

### PGND and AGND

Power and analog ground terminals. The power and analog ground terminals should be connected together with a very low impedance connection.

### V+

V+ terminals are the power supply inputs to the device. All V+ terminals must be connected together on the printed circuit board with as short as possible traces offering as low impedance as possible between terminals.

V+ terminals have an undervoltage threshold. If the supply voltage drops below a V+ undervoltage threshold, the output power stage switches to a tri-state condition and the fault status flag is SET and the Fault Status terminal voltage switched to a logic LOW. When the supply voltage returns to a level that is above the threshold, the power stage automatically resumes normal operation according to the established condition of the input terminals and the fault status flag is automatically reset logic HIGH.

### Fault Status ( $\overline{\text{FS}}$ )

This terminal is the device fault status output. This output is an active LOW open drain structure requiring a pull-up resistor to 5.0 V. Refer to [Table 1, Truth Table](#), page 17.

### IN1, IN2, D1, and $\overline{\text{D2}}$

These terminals are input control terminals used to control the outputs. These terminals are 5.0 V CMOS-compatible inputs with hysteresis. The IN1 and IN2 independently control OUT1 and OUT2, respectively. D1 and  $\overline{\text{D2}}$  are complementary inputs used to tri-state disable the H-Bridge outputs.

When either D1 or  $\overline{\text{D2}}$  is SET (D1 = logic HIGH or  $\overline{\text{D2}}$  = logic LOW) in the disable state, outputs OUT1 and OUT2 are both tri-state disabled; however, the rest of the device circuitry is fully operational and the supply  $I_{Q(\text{standby})}$  current is reduced to a few milliamperes. Refer to [Table 1, Truth Table](#), and [STATIC ELECTRICAL CHARACTERISTICS](#) table, page 8.

### OUT1 and OUT2

These terminals are the outputs of the H-Bridge with integrated output FET body diodes. The bridge output is controlled using the IN1, IN2, D1, and  $\overline{\text{D2}}$  inputs. The outputs have active current limiting above 6.5 A. The outputs also have

thermal shutdown (tri-state latch-OFF) with hysteresis as well as short circuit latch-OFF protection.

A disable timer (time  $t_b$ ) incorporated to detect currents that are higher than current limit is activated at each output activation to facilitate hard short detection (see [Figure 7](#), page 12).

### C<sub>CP</sub>

Charge pump output terminal. A filter capacitor (up to 33 nF) can be connected from the C<sub>CP</sub> terminal and PGND. The device can operate without the external capacitor, although the C<sub>CP</sub> capacitor helps to reduce noise and allows the device to perform at maximum speed, timing, and PWM frequency.

### EN

The EN terminal is used to place the device in a sleep mode so as to consume very low currents. When the EN terminal voltage is a logic LOW state, the device is in the sleep mode. The device is enabled and fully operational when the EN terminal voltage is logic HIGH. An internal pull-down resistor maintains the device in sleep mode in the event EN is driven through a high impedance I/O or an unpowered microcontroller, or the EN input becomes disconnected.

### FB

The device has a feedback output (FB) for “real time” monitoring of H-Bridge high-side current to facilitate closed-loop operation for motor speed and torque control.

The FB terminal provides current sensing feedback of the H-Bridge high-side drivers. When running in the forward or reverse direction, a ground referenced 1/375th (0.00266) of load current is output to this terminal. Through the use of an external resistor to ground, the proportional feedback current can be converted to a proportional voltage equivalent and the controlling microcontroller can “read” the current proportional voltage with its analog-to-digital converter (ADC). This is intended to provide the user with motor current feedback for motor torque control. The accuracy is  $\pm 20\%$  at load currents  $< 1.5$  A and  $\pm 10\%$  at load currents  $> 1.5$  A.

If PWM-ing is implemented using the disable terminal inputs (either D1 or  $\overline{\text{D2}}$ ), a small filter capacitor (1.0  $\mu\text{F}$  or less) may be required in parallel with the external resistor to ground for fast spike suppression.

## PERFORMANCE FEATURES

### Short Circuit Protection

If an output short circuit condition is detected, the power outputs tri-state (latch-OFF) independent of the input (IN1 and IN2) states, and the fault status output flag is SET logic LOW. If the D1 input changes from logic HIGH to logic LOW, or if the  $\overline{D2}$  input changes from logic LOW to logic HIGH, the output bridge will become operational again and the fault status flag will be reset (cleared) to a logic HIGH state.

The output stage will always switch into the mode defined by the input terminals (IN1, IN2, D1, and  $\overline{D2}$ ), provided the device junction temperature is within the specified operating temperature range.

### Active Current Limiting

The maximum current flow under normal operating conditions is internally limited to  $I_{LIM}$  (5.2 A to 7.8 A). When the maximum current value is reached, the output stages are tri-stated for a fixed time ( $t_d$ ) of 20  $\mu$ s typical. Depending on the time constant associated with the load characteristics, the current decreases during the tri-state duration until the next output ON cycle occurs (see [Figures 7](#) and [13](#), page 12 and page 15, respectively).

The current limiting threshold value is dependent upon the device junction temperature. When  $-40^\circ\text{C} \leq T_J \leq 160^\circ\text{C}$ ,  $I_{LIM}$  is between 5.2 A to 7.8 A. When  $T_J$  exceeds  $160^\circ\text{C}$ , the  $I_{LIM}$  current decreases linearly down to 2.5 A typical at  $175^\circ\text{C}$ . Above  $175^\circ\text{C}$  the device overtemperature circuit detects  $T_{LIM}$  and overtemperature shutdown occurs (see [Figure 5](#), page 11). This feature allows the device to remain operational for a longer time but at a regressing output performance level at junction temperatures above  $160^\circ\text{C}$ .

### Overtemperature Shutdown and Hysteresis

If an overtemperature condition occurs, the power outputs are tri-stated (latched-OFF) and the fault status flag is SET to logic LOW.

To reset from this condition, D1 must change from logic HIGH to logic LOW, or  $\overline{D2}$  must change from logic LOW to logic HIGH. When reset, the output stage switches ON again, provided that the junction temperature is now below the overtemperature threshold limit minus the hysteresis.

**Note** Resetting from the fault condition will clear the fault status flag.

## PACKAGE INFORMATION

The 33887 is designed for enhanced thermal performance. The significant feature of this device is the exposed copper pad on which the power die is soldered. This pad is soldered on a PCB to provide heat flow to ambient and also to provide thermal capacitance. The more copper area on the PCB, the better the power dissipation and transient behavior will be.

**Example** Characterization on a double-sided PCB: bottom side area of copper is  $7.8\text{ cm}^2$ ; top surface is  $2.7\text{ cm}^2$  (see [Figure 19](#)); grid array of 24 vias  $0.3\text{ mm}$  in diameter.

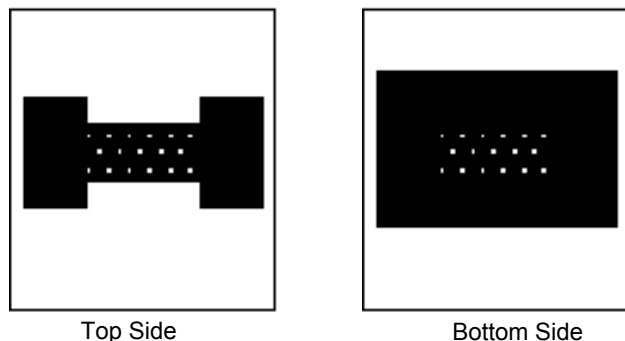


Figure 19. PCB Test Layout

[Figure 20](#) shows the thermal response with the device soldered on to the test PCB described in [Figure 19](#).

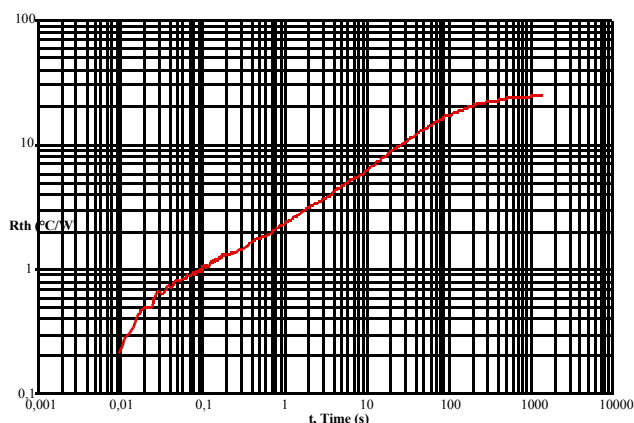


Figure 20. 33887 Thermal Response

## APPLICATIONS

A typical application schematic is shown in [Figure 21](#). For precision high-current applications in harsh, noisy

environments, the V+ by-pass capacitor may need to be substantially larger.

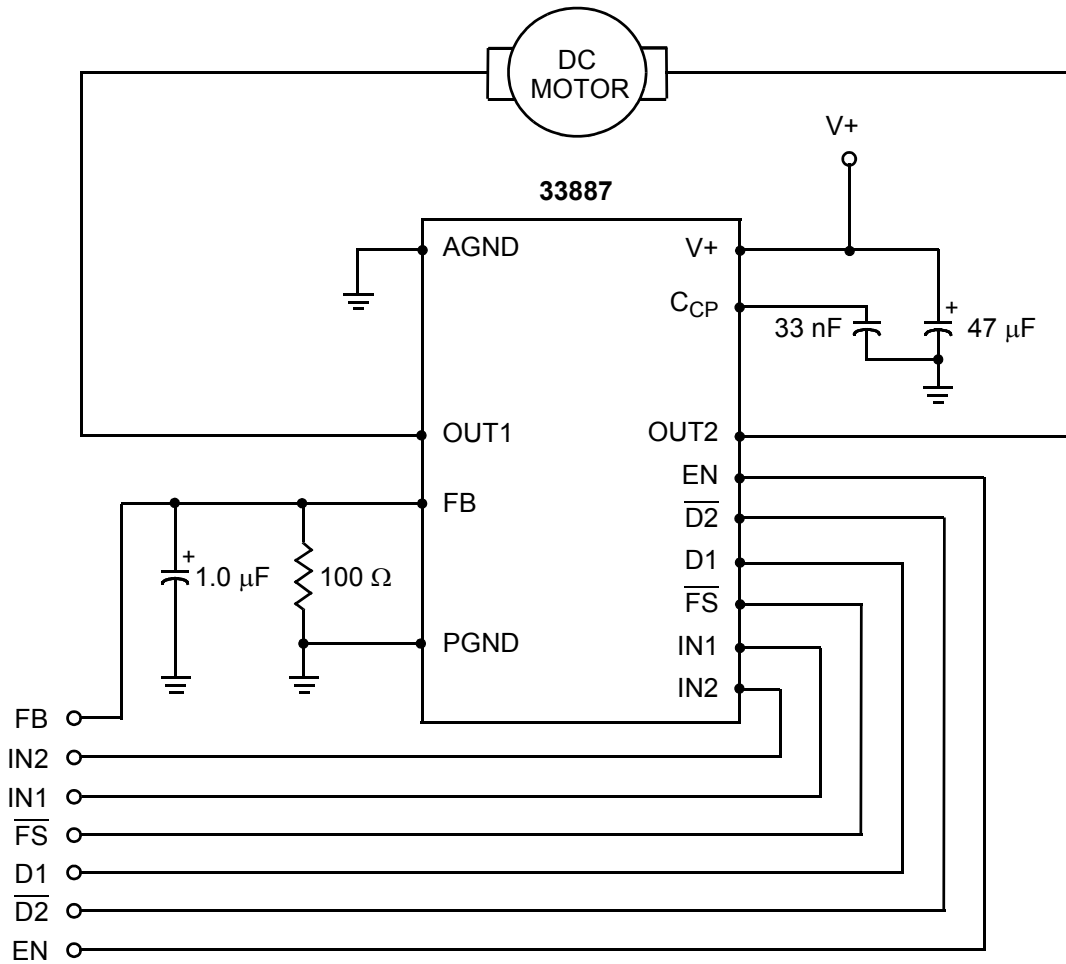
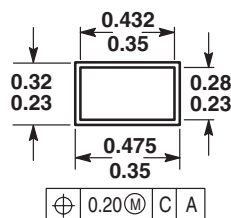
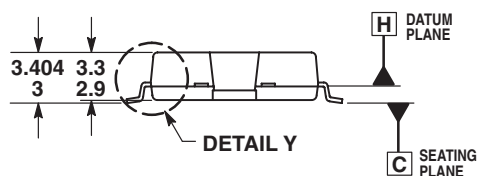
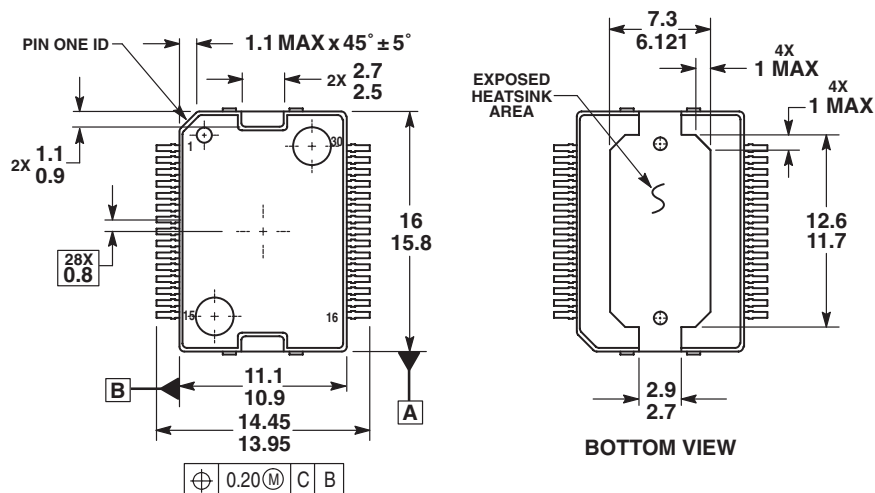


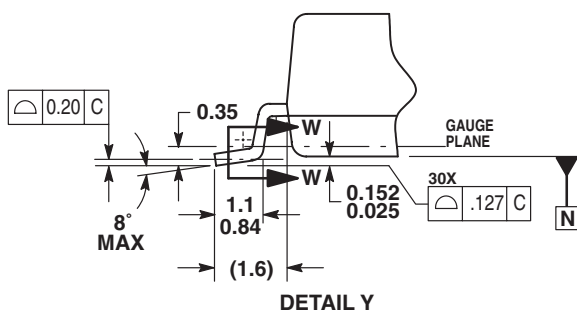
Figure 21. 33887 Typical Application Schematic

## PACKAGE DIMENSIONS

**DH SUFFIX**  
20-TERMINAL HSOP  
PLASTIC PACKAGE  
CASE 979A-09  
ISSUE H



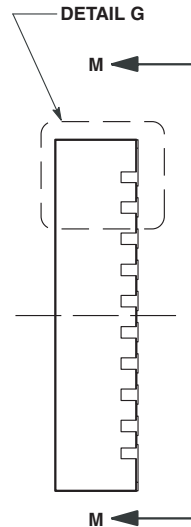
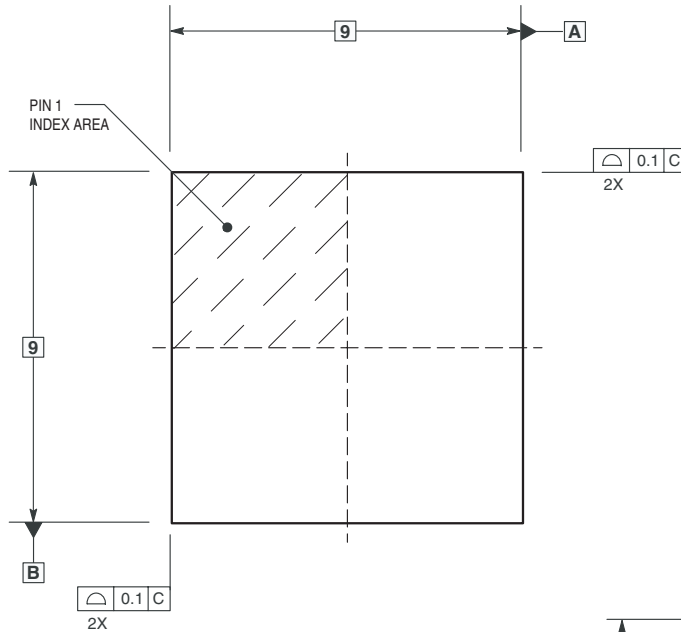
**SECTION W-W**



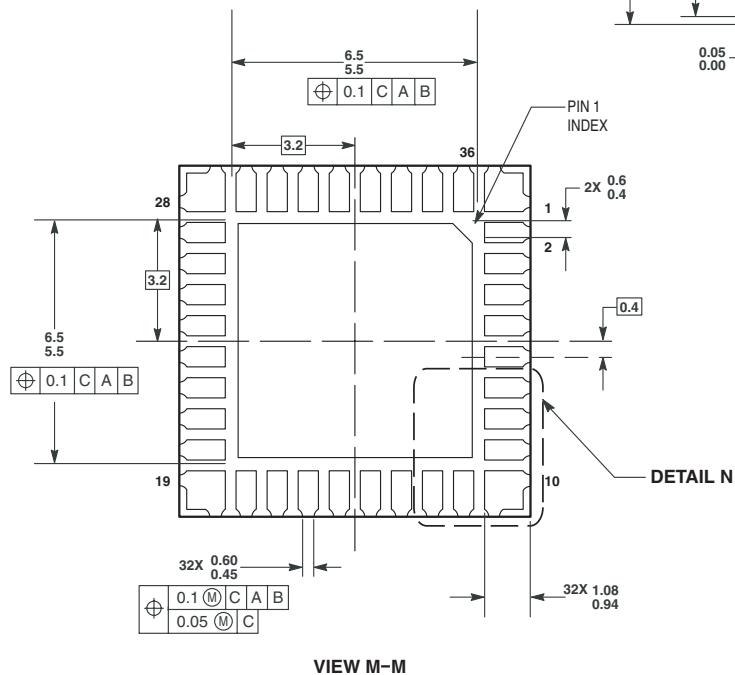
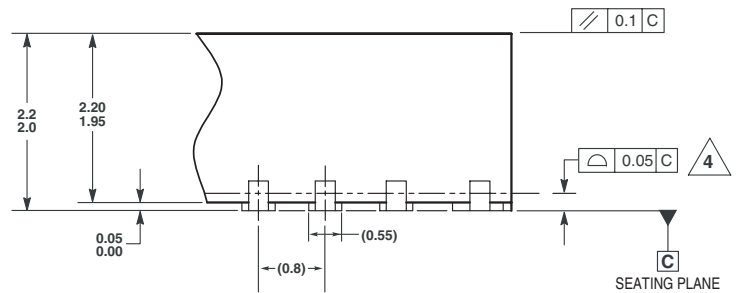
### NOTES:

1. CONTROLLING DIMENSION: MILLIMETER.
2. DIMENSIONS AND TOLERANCES PER ASME Y14.5M, 1994.
3. DATUM PLANE -H- IS LOCATED AT BOTTOM OF LEAD AND IS COINCIDENT WITH THE LEAD WHERE THE LEAD EXITS THE PLASTIC BODY AT THE BOTTOM OF THE PARTING LINE.
4. DIMENSIONS D AND E1 DO NOT INCLUDE MOLD PROTRUSION. ALLOWABLE PROTRUSION IS 0.150 PER SIDE. DIMENSIONS D AND E1 DO INCLUDE MOLD MISMATCH AND ARE DETERMINED AT DATUM PLANE -H-.
5. DIMENSION b DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.127 TOTAL IN EXCESS OF THE b DIMENSION AT MAXIMUM MATERIAL CONDITION.
6. DATUMS -A- AND -B- TO BE DETERMINED AT DATUM PLANE -H-.
7. DIMENSION D DOES NOT INCLUDE TIEBAR PROTRUSIONS. ALLOWABLE TIEBAR PROTRUSIONS ARE 0.150 PER SIDE.

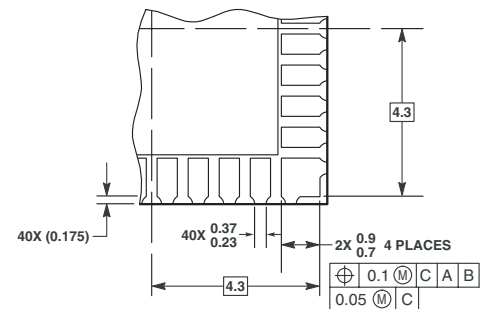
**PNB SUFFIX**  
**36-TERMINAL PQFN**  
**PLASTIC PACKAGE**  
**CASE 1503-01**  
**ISSUE O**



- NOTES:
1. ALL DIMENSIONS ARE IN MILLIMETERS.
  2. DIMENSIONING AND TOLERANCING PER ASME Y14.5M, 1994.
  3. THE COMPLETE JEDEC DESIGNATOR FOR THIS PACKAGE IS: F-PQFP-N.
  4. COPLANARITY APPLIES TO LEADS AND CORNER LEADS.

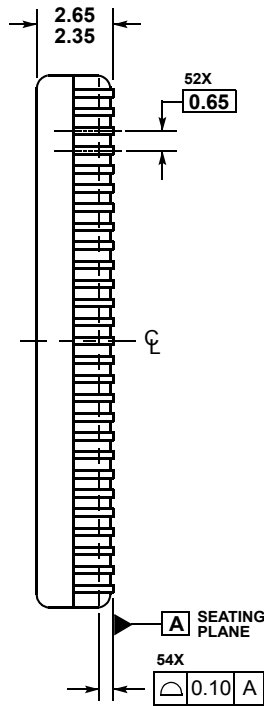
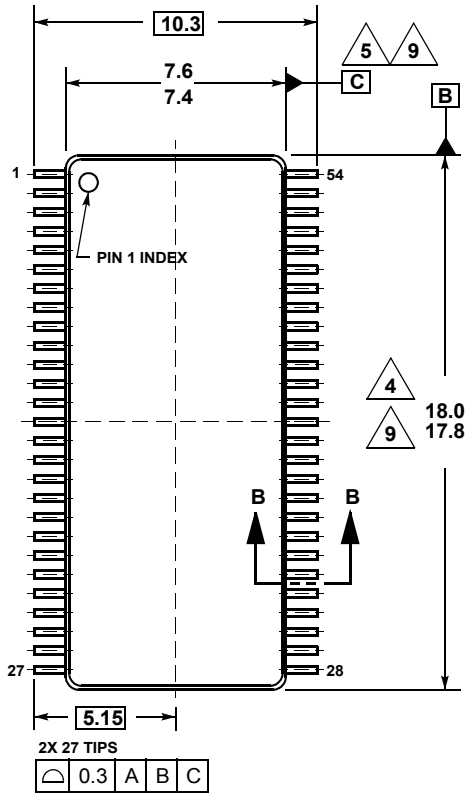


**DETAIL G**  
**VIEW ROTATED 90° CW**



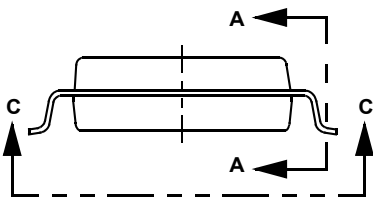
**DETAIL N**  
**CORNER CONFIGURATION**

**DWB SUFFIX**  
**54-TERMINAL SOICW EXPOSED PAD**  
**PLASTIC PACKAGE**  
CASE 1390-01  
ISSUE B

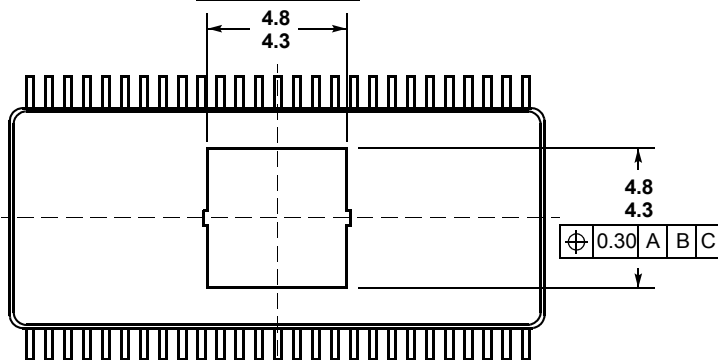


**NOTES:**

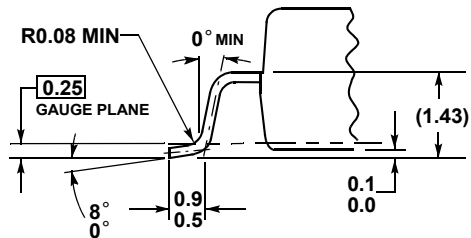
1. ALL DIMENSIONS ARE IN MILLIMETERS.
2. DIMENSIONING AND TOLERANCING PER ASME Y14.5M, 1994.
3. DATUMS B AND C TO BE DETERMINED AT THE PLANE WHERE THE BOTTOM OF THE LEADS EXIT THE PLASTIC BODY.
4. THIS DIMENSION DOES NOT INCLUDE MOLD FLASH, PROTRUSION OR GATE BURRS. MOLD FLASH, PROTRUSION OR GATE BURRS SHALL NOT EXCEED 0.15 MM PER SIDE. THIS DIMENSION IS DETERMINED AT THE PLANE WHERE THE BOTTOM OF THE LEADS EXIT THE PLASTIC BODY.
5. THIS DIMENSION DOES NOT INCLUDE INTERLEAD FLASH OR PROTRUSIONS. INTERLEAD FLASH AND PROTRUSIONS SHALL NOT EXCEED 0.25 MM PER SIDE. THIS DIMENSION IS DETERMINED AT THE PLANE WHERE THE BOTTOM OF THE LEADS EXIT THE PLASTIC BODY.
6. THIS DIMENSION DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL NOT CAUSE THE LEAD WIDTH TO EXCEED 0.46 MM. DAMBAR CANNOT BE LOCATED ON THE LOWER RADIUS OR THE FOOT. MINIMUM SPACE BETWEEN PROTRUSION AND ADJACENT LEAD SHALL NOT LESS THAN 0.07 MM.
7. EXACT SHAPE OF EACH CORNER IS OPTIONAL.
8. THESE DIMENSIONS APPLY TO THE FLAT SECTION OF THE LEAD BETWEEN 0.1 MM AND 0.3 MM FROM THE LEAD TIP.
9. THE PACKAGE TOP MAY BE SMALLER THAN THE PACKAGE BOTTOM. THIS DIMENSION IS DETERMINED AT THE OUTERMOST EXTREMES OF THE PLASTIC BODY EXCLUSIVE OF MOLD FLASH, TIE BAR BURRS, GATE BURRS AND INTER-LEAD FLASH, BUT INCLUDING ANY MISMATCH BETWEEN THE TOP AND BOTTOM OF THE PLASTIC BODY.



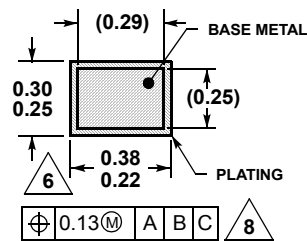
0.30 A B C



**VIEW C-C**



**SECTION B-B**



**SECTION A-A**  
ROTATED 90° CLOCKWISE

## NOTES

## NOTES

## NOTES

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